

Linearised Analysis of the Coxeter Higher Spin Theory I

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Origins

- Relationship between HS and Strings

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- S. E. Konshtein and M. A. Vasiliev, Nucl. Phys. B 312 (1989) 402; R.R. Metsaev, SQS'99; M. Bianchi and V. Didenko, [[arXiv:hep-th/0502220](https://arxiv.org/abs/hep-th/0502220)]; A. Sagnotti and M. Tsulaia, Nucl. Phys. B 682 (2004), 83-116
- M.A. Vasiliev, Class.Quant.Grav. 30 (2013), 104006; M.A. Vasiliev, JHEP 08 (2018), 051

- Tensor $O(N)$ models and its HS dual

- I. R. Klebanov and A. M. Polyakov, Phys. Lett. B 550 (2002) 213; O. Aharony, G. Gur-Ari and R. Yacoby, JHEP 1203 (2012) 037
- I. R. Klebanov and G. Tarnopolsky, Phys. Rev. D 95 (2017) no.4, 046004

Coxeter groups

Rank- p Coxeter group \mathcal{C} is generated by reflections with respect to a system of root vectors $\{v_a\}$ in a p -dimensional Euclidean vector space V . An elementary reflection associated with the root vector v_a :

$$R_{v_a} x^i = x^i - 2 \frac{(v_a, x)}{(v_a, v_a)} v_a^i, \quad R_{v_a}^2 = Id.$$

Coxeter groups: examples

- The root system of $A_p \simeq S_{p+1}$: $v^{ij} = e^i - e^j$, with orthonormal frame e^i in \mathbb{R}^{p+1} . V is the p -dimensional subspace in \mathbb{R}^{p+1} spanned by v^{ij} .
- The root system of $B_p \simeq S_p \ltimes (\mathbb{Z}_2)^p$ consists of two conjugacy classes

$$\mathcal{R}_1 = \{\pm e^i, 1 \leq i \leq p\}, \quad \mathcal{R}_2 = \{\pm e^i \pm e^j, 1 \leq i < j \leq p\}.$$

Framed Cherednik algebra

Generators I_n , q_α^n and \hat{K}_v for each root vector v (here $\alpha \in \{1, 2\}$, $n \in \{1, \dots, p\}$):

$$I_n I_m = I_m I_n, \quad I_n I_n = I_n, \quad I_n q_\alpha^n = q_\alpha^n I_n = q_\alpha^n, \quad I_m q_\alpha^n = q_\alpha^n I_m,$$

$$\hat{K}_v q_\alpha^n = R_v {}^n{}_m q_\alpha^m \hat{K}_v, \quad \hat{K}_v \hat{K}_u = \hat{K}_u \hat{K}_{R_u(v)} = \hat{K}_{R_v(u)} \hat{K}_v,$$

$$\hat{K}_v \hat{K}_v = \prod I_{i_1(v)} \dots I_{i_k(v)}, \quad \hat{K}_v = \hat{K}_{-v},$$

Labels $i_1(v), \dots, i_k(v)$ enumerate idempotents I_n affected by the reflection R_v .

Framed Cherednik algebra

$$[q_\alpha^n, q_\beta^m] = -i\varepsilon_{\alpha\beta} \left(2\delta^{nm} I_n + \sum_{v \in \mathcal{R}} \nu(v) \frac{v^n v^m}{(v, v)} \hat{K}_v \right),$$

where \mathcal{R} is a set of conjugacy classes of root vectors, $\nu(v)$ is a function of conjugacy classes.

Klein operators \hat{K}_v obey

$$I_n \hat{K}_v = \hat{K}_v I_n, \forall n \in \{1, \dots, p\},$$

$$I_n \hat{K}_v = \hat{K}_v I_n = \hat{K}_v, \forall n \in \{i_1(v), \dots, i_k(v)\}.$$

Following M.A. Vasiliev, JHEP 08 (2018), 051

CHS model setup

Fields $W(Y, Z; \hat{K}|x)$, $S(Y, Z; \hat{K}|x)$ and $B(Y, Z; \hat{K}|x)$ which depend on Y_A^n, Z_A^n ($A \in \{1, \dots, 4\}$, $n \in \{1, \dots, p\}$), idempotents I_n , differentials dZ_n^A and operators \hat{K}_v associated with \mathcal{C} .

The star product

$$(f * g)(Y, Z, I) = \frac{1}{(2\pi)^{4p}} \int d^{4p}S d^{4p}T \exp\left(i S_n^A T_m^B C_{AB} \delta^{nm}\right) f(Y_i + I_i S_i, Z_i + I_i S_i, I) g(Y + T, Z - T, I),$$

where

$$C_{AB} = \begin{pmatrix} \epsilon_{\alpha\beta} & 0 \\ 0 & \bar{\epsilon}_{\dot{\alpha}\dot{\beta}} \end{pmatrix}.$$

CHS algebra

It is demanded that

$$Y_A^m * I_n = I_n * Y_A^m, \quad Y_A^n * I_n = I_n * Y_A^n = Y_A^n, \\ I_n * I_n = I_n, \quad I_n * I_m = I_m * I_n.$$

Z_A^n obeys analogous conditions.

From the star product and properties of I_n it follows

$$[Y_A^n, Y_B^m]_* = -[Z_A^n, Z_B^m]_* = 2iC_{AB}\delta^{nm}I_n, \quad [Y_A^n, Z_B^m]_* = 0.$$

The star product admits inner Klein operators \varkappa_v , $\bar{\varkappa}_v$ associated with the root vectors v

$$\varkappa_v = \exp\left(i \frac{v^n v^m}{(v, v)} z_{\alpha n} y_m^\alpha\right), \quad \bar{\varkappa}_v = \exp\left(i \frac{v^n v^m}{(v, v)} \bar{z}_{\dot{\alpha} n} \bar{y}_m^{\dot{\alpha}}\right),$$

$$\varkappa_v * q_\alpha^n = R_v{}^n{}_m q_\alpha^m * \varkappa_v, \quad q_\alpha^n = y_\alpha^n, z_\alpha^n.$$

CHS equations

Nonlinear equations for the generalized CHS theory are

$$d_x W + W * W = 0, \quad (1)$$

$$d_x B + W * B - B * W = 0, \quad (2)$$

$$d_x S + W * S + W * S = 0, \quad (3)$$

$$S * B = B * S, \quad (4)$$

$$\begin{aligned} S * S = i \left(dZ^{A_n} dZ_{A_n} + \sum_i \sum_{v \in \mathcal{R}_i} \left[F_{i*}(B) \frac{v^n v^m}{(v, v)} dz_n^\alpha dz_{\alpha m} * \varkappa_v \hat{k}_v + \right. \right. \\ \left. \left. + \bar{F}_{i*}(B) \frac{v^n v^m}{(v, v)} d\bar{z}_n^{\dot{\alpha}} d\bar{z}_{\dot{\alpha} m} * \bar{\varkappa}_v \hat{\bar{k}}_v \right] \right), \quad (5) \end{aligned}$$

where $\varkappa_v \hat{k}_v$ acts on dz_n^α as

$$\varkappa_v \hat{k}_v * dz_n^\alpha = R_{vn}{}^m dz_m^\alpha * \varkappa_v \hat{k}_v,$$

$F_{i*}(B)$ is any star-product function of B on the conjugacy classes \mathcal{R}_i of \mathcal{C} . We set $F_{i*}(B) = \eta_i B$.

Following M.A. Vasiliev, JHEP 08 (2018), 051

AdS_4 solution

The vacuum solution

$$B_0 = 0, \quad S_0 = dZ^{A_n} Z_{A_n}, \quad W = W_0(Y, I|x)$$

with flat $W_0(Y, I|x)$

$$d_x W_0(Y, I|x) + W_0(Y, I|x) * W_0(Y, I|x) = 0.$$

In a general CHS theory, AdS_4 is represented by a dx one-form

$$\Omega_{AdS}(Y|x) = -\frac{i}{4}\delta^{nm}\left(\omega_{\alpha\beta}(x)y_n^\alpha y_m^\beta + \bar{\omega}_{\dot{\alpha}\dot{\beta}}(x)\bar{y}_n^{\dot{\alpha}}\bar{y}_m^{\dot{\beta}} + 2h_{\alpha\dot{\alpha}}(x)y_n^\alpha\bar{y}_m^{\dot{\alpha}}\right).$$

The AdS_4 connection has no explicit dependence on idempotents I_n .

Covariant derivatives

The covariant derivative is

$$\begin{aligned} D_\Omega f(Y; \hat{k}, \hat{\bar{k}}|x) &= D_L f(Y; \hat{k}, \hat{\bar{k}}|x) + \\ &+ \frac{1}{2} \delta^{nm} h^{\alpha\dot{\alpha}} \left(\mathbb{1}_n^k \bar{\mathbb{1}}_m^l + R(k)_n^k \bar{R}(\bar{k})_m^l \right) (y_{\alpha k} I_l \bar{\partial}_{\dot{\alpha} l} + \bar{y}_{\dot{\alpha} l} I_k \partial_{\alpha k}) f(Y; \hat{k}, \hat{\bar{k}}|x) - \\ &- \frac{i}{2} \delta^{nm} h^{\alpha\dot{\alpha}} \left(\mathbb{1}_n^k \bar{\mathbb{1}}_m^l - R(k)_n^k \bar{R}(\bar{k})_m^l \right) (y_{\alpha k} \bar{y}_{\dot{\alpha} l} - I_k I_l \partial_{\alpha k} \bar{\partial}_{\dot{\alpha} l}) f(Y; \hat{k}, \hat{\bar{k}}|x), \end{aligned}$$

where $\mathbb{1}_n^k$ and $\bar{\mathbb{1}}_m^l$ are identity matrices, \hat{k} and $\hat{\bar{k}}$ are products of \hat{k}_v and $\hat{\bar{k}}_v$, matrices $R(k)_n^k$ and $\bar{R}(\bar{k})_m^l$ are corresponding reflections in the root space.

General observation about modules

- If $P_{\pm}^{kl} = \frac{1}{2}\delta^{nm}\left(\mathbb{1}_n^k\bar{\mathbb{1}}_m^l \pm R(k)_n^k\bar{R}(\bar{k})_m^l\right)$ is a set of orthogonal projectors, i.e., $(R\bar{R})^2 = \mathbb{1}$, then the CHS module is a product of adjoint and twisted-adjoint modules of standard HS.
- If P_{\pm}^{kl} are not projectors, i.e., $(R\bar{R})^2 \neq \mathbb{1}$, then the CHS module is a product of standard HS modules and infinite-dimensional entangled modules of the new type.
- Both cases appear for any nontrivial (not \mathbb{Z}_2) group \mathcal{C} .

Group B_2

The root system of B_2 has two conjugacy classes

$$\mathcal{R}_1 = \{\pm e^1, \pm e^2\}, \quad \mathcal{R}_2 = \{\pm e^1 \pm e^2\}.$$

The group B_2 is generated by

$$\left\{ k_i, k_{12} \mid k_i^2 = 1, k_{12}^2 = 1, k_1 k_{12} = k_{12} k_2, k_2 k_{12} = k_{12} k_1, i \in \{1, 2\} \right\}.$$

Group B_2

For reflection matrices $R(k)$ we have

$$R(1) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, R(k_1) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, R(k_2) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix},$$
$$R(k_{12}) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, R(k_1 k_2) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, R(k_1 k_{12}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix},$$
$$R(k_2 k_{12}) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, R(k_1 k_2 k_{12}) = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}.$$

Analogous matching occurs for $\bar{R}(\bar{k})$.

B_2 equations

All possible matrix products $R(k)\bar{R}(\bar{k})$ group into the 8 categories

$$R(k)\bar{R}(\bar{k}) = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \right. \\ \left. \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right\},$$

inducing 8 types of covariant constancy equations on the component fields

$$C(Y_1, Y_2; \hat{k}, \bar{\hat{k}}|x) = \sum_{a,b,c,\bar{a},\bar{b},\bar{c}=0}^1 C_{abc\bar{a}\bar{b}\bar{c}}(Y_1, Y_2|x) \hat{k}_1^a \hat{k}_2^b \hat{k}_{12}^c \hat{\bar{k}}_1^{\bar{a}} \hat{\bar{k}}_2^{\bar{b}} \hat{\bar{k}}_{12}^{\bar{c}}.$$

B_2 equations

For instance,

$$R(k)\bar{R}(\bar{k}) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

\Updownarrow

$$\left(D_L + h^{\alpha\dot{\alpha}} \sum_{i=1}^2 (y_{\alpha i} \bar{\partial}_{\dot{\alpha} i} + \bar{y}_{\dot{\alpha} i} \partial_{\alpha i}) \right) C(Y; \hat{K}|x) = 0 ,$$

$$R(k)\bar{R}(\bar{k}) = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

\Updownarrow

$$\left(D_L - ih^{\alpha\dot{\alpha}} \sum_{i=1}^2 (y_{\alpha i} \bar{y}_{\dot{\alpha} i} - \partial_{\alpha i} \bar{\partial}_{\dot{\alpha} i}) \right) C(Y; \hat{K}|x) = 0 ,$$

B_2 equations

$$R(k)\bar{R}(\bar{k}) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

⇓

$$\left(D_L - ih^{\alpha\dot{\alpha}}(y_{\alpha 1}\bar{y}_{\dot{\alpha}1} - \partial_{\alpha 1}\bar{\partial}_{\dot{\alpha}1}) + h^{\alpha\dot{\alpha}}(y_{\alpha 2}\bar{\partial}_{\dot{\alpha}2} + \bar{y}_{\dot{\alpha}2}\partial_{\alpha 2}) \right) C(Y; \hat{K}|x) = 0,$$

$$R(k)\bar{R}(\bar{k}) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

⇓

$$\left(D_L + \frac{1}{2}h^{\alpha\dot{\alpha}} \left[(y_{\alpha 1} + y_{\alpha 2})(\bar{\partial}_{\dot{\alpha}1} + \bar{\partial}_{\dot{\alpha}2}) + (\bar{y}_{\dot{\alpha}1} + \bar{y}_{\dot{\alpha}2})(\partial_{\alpha 1} + \partial_{\alpha 2}) \right] - \right.$$

$$\left. - \frac{i}{2}h^{\alpha\dot{\alpha}} \left[(y_{\alpha 1} - y_{\alpha 2})(\bar{y}_{\dot{\alpha}1} - \bar{y}_{\dot{\alpha}2}) - (\partial_{\alpha 1} - \partial_{\alpha 2})(\bar{\partial}_{\dot{\alpha}1} - \bar{\partial}_{\dot{\alpha}2}) \right] \right) C(Y; \hat{K}|x) = 0,$$

B_2 equations

$$R(k)\bar{R}(\bar{k}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$
$$\Updownarrow$$
$$\left(D_L + \frac{1}{2} h^{\alpha\dot{\alpha}} \left[y_{\alpha 1} (\bar{\partial}_{\dot{\alpha} 1} - \bar{\partial}_{\dot{\alpha} 2}) + y_{\alpha 2} (\bar{\partial}_{\dot{\alpha} 1} + \bar{\partial}_{\dot{\alpha} 2}) + \bar{y}_{\dot{\alpha} 1} (\partial_{\alpha 1} + \partial_{\alpha 2} - \bar{y}_{\dot{\alpha} 2} (\partial_{\alpha 1} - \partial_{\alpha 2})) \right] - \frac{i}{2} h^{\alpha\dot{\alpha}} \left[y_{\alpha 1} (\bar{y}_{\dot{\alpha} 1} + \bar{y}_{\dot{\alpha} 2}) - y_{\alpha 2} (\bar{y}_{\dot{\alpha} 1} - \bar{y}_{\dot{\alpha} 2}) - \partial_{\alpha 1} (\bar{\partial}_{\dot{\alpha} 1} + \bar{\partial}_{\dot{\alpha} 2}) + \partial_{\alpha 2} (\bar{\partial}_{\dot{\alpha} 1} - \bar{\partial}_{\dot{\alpha} 2}) \right] \right) C(Y_1, Y_2; \hat{k}, \bar{\hat{k}} | x) = 0.$$

Entangled module

$$R(k)\bar{R}(\bar{k}) = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$
$$\Updownarrow$$

Ansatz $C(Y_1, Y_2; \hat{k}, \hat{\bar{k}}|x) = e^{-iy_{1\alpha}y_2^\alpha + i\bar{y}_{1\dot{\alpha}}\bar{y}_2^{\dot{\alpha}}} \tilde{C}(Y_1, Y_2; \hat{k}, \hat{\bar{k}}|x)$

$$\left[D_L - ih^{\alpha\dot{\alpha}} \left(y_{1\alpha}\bar{y}_{1\dot{\alpha}} + y_{2\alpha}\bar{y}_{2\dot{\alpha}} + y_{1\alpha}\bar{y}_{2\dot{\alpha}} - y_{2\alpha}\bar{y}_{1\dot{\alpha}} \right) + \right. \\ \left. + \frac{i}{2}h^{\alpha\dot{\alpha}} \left(\partial_{1\alpha}\bar{\partial}_{1\dot{\alpha}} + \partial_{2\alpha}\bar{\partial}_{2\dot{\alpha}} + \partial_{1\alpha}\bar{\partial}_{2\dot{\alpha}} - \partial_{2\alpha}\bar{\partial}_{1\dot{\alpha}} \right) \right] \tilde{C}(Y_1, Y_2; \hat{k}, \hat{\bar{k}}|x) = 0.$$

Unitarity and boundary conditions

- CHS modules with adjoint part can be restricted to the unitary submodules.
- Restriction in terms of the boundary condition in the stereographic coordinates of AdS_4

$$\lim_{z \rightarrow 0} \frac{1}{\sqrt{z}} C(Y_1, Y_2; \hat{K}|x) = 0,$$

where

$$x_{\alpha\dot{\beta}} = \sigma^a_{\alpha\dot{\beta}} x_a, \quad x^2 = x_a x^a = \frac{1}{2} x_{\alpha\dot{\beta}} x^{\alpha\dot{\beta}}, \quad z = 1 + x^2.$$