## Unfolded formulation of 4d Yang–Mills theory (to appear on arXiv:2408.13212)

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### outline

- unfolded dynamics approach of higher-spin gravity
- derivation of unfolded Yang–Mills equations
- interpretation of unfolded equations in terms of unfolding maps

# unfolded dynamics approach

- higher-spin (HS) gravity a nonlinear gauge theory of interacting massless fields of all spins (including graviton) possessing ∞-dim HS gauge symmetry;
- to formulate the theory in a manifestly diffeomorphism- and gauge-invariant way [Vasiliev'89-94], a special first-order formalism was developed called unfolded dynamics approach [Vasiliev hep-th/0504090];
- it is interesting to apply it to different theories
- constructing unfolded formulations (especially nonlinear) is not easy
- many examples of unfolding linear theories are known, e.g. [Shaynkman, Vasiliev hep-th/0003123; Ponomarev, Vasiliev 1012.2903; Khabarov, Zinoviev 2001.07903; Buchbinder, Snegirev, Zinoviev 1606.02475; NM'19-'23].
- but not so many nonlinear theories beyond HS [Joung, Kim, Kim 2108.05535; NM 2208.04306, 2402.14164].
- method of quantization of unfolded field theories was proposed [NM 2208.04306].

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## unfolded dynamics approach

Unfolded equations are first-order exterior-form equations

$$dW^{A}(x) + G^{A}(W) = 0,$$
 (1)

- Unfolded fields are exterior forms; dynamical field theories require ∞ of unfolded fields encoding all d.o.f. (auxiliary generating variables are handy)
- **Consistency** condition

$$d^2 \equiv 0 \quad \Rightarrow \quad G^B \frac{\delta G^A}{\delta W^B} \equiv 0.$$
 (2)

Unfolded gauge symmetries

$$\delta W^{A} = \mathrm{d}\varepsilon^{A}(\mathbf{x}) - \varepsilon^{B} \frac{\delta G^{A}}{\delta W^{B}}.$$
(3)

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- Unfolded fields form modules for all symmetries of the theory, realized algebraically.
- Gauge symmetries are associated with (n > 0)-forms, 0-forms correspond to physical d.o.f. which transform only passively under 1-form symmetries.

## Yang-Mills equations in spinorial notations

• 4d YM equations + Bianchi identities in sl(2, C)-spinor notations

$$D_{\beta\dot{\alpha}}F^{\beta}{}_{\alpha}=0, \quad D_{\alpha\dot{\beta}}\bar{F}^{\dot{\beta}}{}_{\dot{\alpha}}=0, \tag{4}$$

• (anti-)selfdual YM strength tensor

$$F_{\alpha\alpha} := \frac{\partial}{\partial x^{\alpha\dot{\beta}}} A_{\alpha}{}^{\dot{\beta}} - i[A_{\alpha\dot{\beta}}, A_{\alpha}{}^{\dot{\beta}}], \quad \bar{F}_{\dot{\alpha}\dot{\alpha}} := \frac{\partial}{\partial x^{\beta\dot{\alpha}}} A^{\beta}{}_{\dot{\alpha}} - i[A_{\beta\dot{\alpha}}, A^{\beta}{}_{\dot{\alpha}}], \tag{5}$$

covariant derivative

$$\mathsf{D}_{a\dot{a}} := \frac{\partial}{\partial x^{a\dot{a}}} - i[A_{a\dot{a}}, \bullet], \tag{6}$$

$$[\mathsf{D}_{\alpha\dot{\alpha}},\mathsf{D}_{\beta\dot{\beta}}] = -i\epsilon_{\alpha\beta}\bar{F}_{\dot{\alpha}\dot{\beta}} - i\epsilon_{\dot{\alpha}\dot{\beta}}F_{\alpha\beta}.$$
(7)

- $\epsilon_{\alpha\beta}$  is 2x2 antisymmetric spinor metric
- same-letter indices of multispinors are either contracted or symmetrized

$$T_{\alpha\alpha} := T_{(\alpha_1 \alpha_2)}, \quad T_{\alpha}^{\ \alpha} := \epsilon^{\alpha\beta} T_{\alpha\beta}. \tag{8}$$

## unfolded Yang-Mills field and auxiliary spinors

- In order to unfold Yang–Mills theory, one has to introduce, on top of primaries F<sub>αα</sub> and F<sub>άά</sub>, the infinite towers of all their differential on-shell descendants.
- It's convenient to introduce auxiliary commuting spinors  $Y = (y^{\alpha}, \bar{y}^{\dot{\alpha}})$
- Then the whole towers get packed into unfolded Yang–Mills master-fields, which we postulate to be of the form (here  $Dy\bar{y} := y^{\alpha}\bar{y}^{\dot{\alpha}}D_{\alpha\dot{\alpha}}$ )

$$F(Y|x) = e^{\mathrm{D}y\bar{y}}F_{\alpha\alpha}(x)y^{\alpha}y^{\alpha}e^{-\mathrm{D}y\bar{y}}, \quad \bar{F}(Y|x) = e^{\mathrm{D}y\bar{y}}\bar{F}_{\dot{\alpha}\dot{\alpha}}(x)\bar{y}^{\dot{\alpha}}\bar{y}^{\dot{\alpha}}e^{-\mathrm{D}y\bar{y}}.$$
(9)

- Unfolded master-field *F* contains the primary Yang-Mills tensor, together with an infinite sequence of its fully symmetrized traceless covariant derivatives of all orders. If *F*<sub>αα</sub> is on-shell, this constitutes a set of all its independent covariant descendants.
- By construction, F takes values in the adjoint representation of the gauge algebra.
- To formulate the unfolded equations, one needs to express the derivatives of the unfolded fields in algebraic terms, which in this case means

$$\mathsf{D}_{\alpha\dot{\beta}}F = (Y,\partial/\partial Y)_{\alpha\dot{\beta}}(F,\bar{F}) \tag{10}$$

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## unfolding map and operator relations

• Introduce the "unfolding map" for an arbitrary function  $C_{\alpha(n),\dot{\beta}(m)}(Y|x)$ 

$$\ll C_{\alpha(n),\dot{\beta}(m)}(Y|x) \gg := e^{Dy\bar{y}} C_{\alpha(n),\dot{\beta}(m)}(Y|x) e^{-Dy\bar{y}}, \qquad (11)$$

In particular,

$$F(Y|x) = \ll F_{\alpha\alpha}(x)y^{\alpha}y^{\alpha} \gg, \quad \bar{F}(Y|x) = \ll \bar{F}_{\dot{\alpha}\dot{\alpha}}(x)\bar{y}^{\dot{\alpha}}\bar{y}^{\dot{\alpha}} \gg.$$
(12)

Making use of two relations,

$$[\hat{A}, e^{\hat{D}}] = \int_{0}^{1} dt e^{t\hat{D}}[\hat{A}, \hat{D}] e^{-t\hat{D}} e^{\hat{D}}, \quad \int_{0}^{1} dt t^{k} F(tz) = \frac{1}{z\frac{\partial}{\partial z} + 1 + k} F(z),$$
(13)

one deduces

$$\ll \partial_{\mu} \mathcal{C} \gg = (\partial_{\mu} - \mathcal{D}_{\mu\dot{\alpha}} \bar{y}^{\dot{\alpha}}) \ll \mathcal{C} \gg + i y_{\mu} [\frac{1}{(N+1)(N+2)} \bar{F}, \ll \mathcal{C} \gg].$$
(14)

where spinorial Euler operators are

$$N := y^{\alpha} \partial_{\alpha}, \quad \bar{N} := \bar{y}^{\dot{\alpha}} \bar{\partial}_{\dot{\alpha}}. \tag{15}$$

### separating the variables

• Direct application of  $[\hat{A}, e^{\hat{D}}]$ -formula gives

$$\mathsf{D}_{\alpha\dot{\beta}}F = [\frac{1}{N} \ll [\mathsf{D}_{\alpha\dot{\beta}}, \mathsf{D}y\bar{y}] \gg, F] + \ll \mathsf{D}_{\alpha\dot{\beta}}F_{\mu\mu}y^{\mu}y^{\mu} \gg .$$
(16)

The task is to bring it to the form with separated variables

$$\mathsf{D}_{\alpha\dot{\beta}}F = (Y,\partial/\partial Y)_{\alpha\dot{\beta}}(F,\bar{F}) \tag{17}$$

- The tools available: YM e.o.m.,  $[D_{\alpha\dot{\alpha}}, D_{\beta\dot{\beta}}]$ , the relation for  $\ll \partial_{\mu}C \gg$ , Schouten indentities for spinors, Jacobi identity of the gauge Lie algebra.
- Applying some of them, one has

$$D_{\mu\mu}F = \bar{y}_{\mu}\left[\frac{i}{2N} \ll \partial_{\mu}F_{\alpha\alpha}y^{\alpha}y^{\alpha} \gg, F\right] + y_{\mu}\left[\frac{i}{2\bar{N}} \ll \bar{\partial}_{\mu}\bar{F}_{\dot{\alpha}\dot{\alpha}}\bar{y}^{\dot{\alpha}}\bar{y}^{\dot{\alpha}} \gg, F\right] + \frac{1}{3} \ll \partial_{\mu}\bar{\partial}_{\dot{\mu}}Dy\bar{y}F_{\alpha\alpha}y^{\alpha}y^{\alpha} \gg .$$
(18)

• Process the first term on the r.h.s. The problem is  $\ll \partial_{\mu}F_{\alpha\alpha}y^{\alpha}y^{\alpha} \gg$ .

### separating the variables

• Applying  $\ll \partial_{\mu} C \gg$ -formula, one has

$$\ll \partial_{\mu}F_{\alpha\alpha}y^{\alpha}y^{\alpha} \gg = \partial_{\mu}F - \mathcal{D}_{\mu\dot{\alpha}}\bar{y}^{\dot{\alpha}}F + iy_{\mu}[\frac{1}{(N+1)(N+2)}\bar{F}, F].$$
(19)

Now, problematic is  $D_{\mu \dot{\alpha}} \bar{y}^{\dot{\alpha}} F.$  Contracting  $D_{\mu \dot{\mu}} F$  with  $\bar{y}^{\dot{\mu}}$  yields

$$\mathsf{D}_{\mu\dot{\alpha}}\bar{y}^{\dot{\alpha}}F = iy_{\mu}[\frac{1}{N+1}\bar{F},F] + \frac{1}{3} \ll \partial_{\mu}\mathsf{D}y\bar{y}F_{\alpha\alpha}y^{\alpha}y^{\alpha} \gg .$$
(20)

This way one finds

$$\ll \partial_{\mu}F_{\alpha\alpha}y^{\alpha}y^{\alpha} \gg = \frac{2}{N+1}(\partial_{\mu}F - iy_{\mu}[\frac{1}{N+2}\bar{F},F]). \tag{21}$$

Proceeding this way, the final result is

$$D_{\mu\bar{\mu}}F = \frac{1}{N+1}\partial_{\mu}\bar{\partial}_{\mu}F + iN[\frac{1}{N(N+1)}\bar{y}_{\mu}\partial_{\mu}F, \frac{1}{N}F] - iy_{\mu}\bar{\partial}_{\mu}\frac{1}{N+2}[\frac{1}{N+2}\bar{F}, F] + \\ +[\frac{i}{(N+1)(N+2)}y_{\mu}\bar{\partial}_{\mu}\bar{F}, F] + \frac{1}{2}y_{\mu}\bar{y}_{\mu}[\frac{N+3}{(N+1)(N+2)}[\frac{1}{N+2}\bar{F}, F], F] + \\ +\frac{3}{2}y_{\mu}\bar{y}_{\mu}[\frac{1}{(N+1)(N+2)}[\frac{1}{N}F, \bar{F}], F] + y_{\mu}\bar{y}_{\mu}[\frac{1}{N+2}[\frac{1}{N+2}\bar{F}, F], \frac{1}{N}F].$$
(22)

# Poincaré symmetry and diffeomorphism-invariance

- Up to now, Cartesian coordinates was used  $(\frac{\partial}{\partial x^{\mu\mu}}$  in  $D_{\mu\mu})$ . Manifest coordinate-independence requires exterior-form formalism.
- To implement global Poincaré symmetry, introduce a 1-form  $\Omega(x) \in iso(1,3)$

$$\Omega = e^{\alpha\beta} P_{\alpha\dot{\beta}} + \omega^{\alpha\alpha} M_{\alpha\alpha} + \bar{\omega}^{\dot{\alpha}\dot{\alpha}} \bar{M}_{\dot{\alpha}\dot{\alpha}}, \qquad (23)$$

where P, M are iso(1, 3)-generators, e and  $\omega$  are 1-forms of a vierbein and a Lorentz connection.

•  $\Omega$  is subjected to the flatness condition

$$\mathrm{d}\Omega + \frac{1}{2}[\Omega,\Omega] = 0, \qquad (24)$$

$$\delta \Omega = d\varepsilon(x) + [\Omega, \varepsilon]$$
(25)

with a gauge symmetry that describes  $\infty\text{-dim}$  freedom in switching between all possible local coordinates on  $\mathbb{R}^{1,3}.$ 

 The gauge symmetry boils down to 10-dim global Poincaré symmetry after fixing some particular solution Ω<sub>0</sub> and restricting to ε(x) which leave it invariant

$$\mathsf{d}\varepsilon_0 + [\Omega_0, \varepsilon_0] = 0.$$

## Poincaré symmetry and diffeomorphism-invariance

• The simplest non-degenerate particular solution – Cartesian coordinates

$$e_{\underline{m}}^{\ \alpha\dot{\beta}} = (\bar{\sigma}_{\underline{m}})^{\dot{\beta}\alpha}, \quad \omega_{\underline{m}}^{\ \alpha\alpha} = 0, \quad \bar{\omega}_{\underline{m}}^{\dot{\alpha}\dot{\alpha}} = 0,$$
 (27)

with global symmetries parameterized by x-independent  $\xi^{\alpha\dot{\beta}}$ ,  $\xi^{\alpha\alpha}$  and  $\bar{\xi}^{\dot{\alpha}\dot{\alpha}}$  as

$$\varepsilon_{glob}^{\alpha\alpha} = \xi^{\alpha\alpha}, \quad \bar{\varepsilon}_{glob}^{\dot{\alpha}\dot{\alpha}} = \bar{\xi}^{\dot{\alpha}\dot{\alpha}}, \quad \varepsilon_{glob}^{\alpha\dot{\beta}} = \xi^{\alpha\dot{\beta}} + \xi^{\alpha}{}_{\gamma}(\bar{\sigma}_{\underline{m}})^{\dot{\beta}\gamma}x^{\underline{m}} + \bar{\xi}^{\dot{\beta}}{}_{\dot{\gamma}}(\bar{\sigma}_{\underline{m}})^{\dot{\gamma}\alpha}x^{\underline{m}}.$$
(28)

• To implement the Yang–Mills gauge symmetry, introduce a 1-form A(x) as

$$A(x) = e^{\alpha \dot{\alpha}} A_{\alpha \dot{\alpha}}.$$
 (29)

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• An appropriate coordinate-independent generalization of  $D_{\mu\mu}$  is a 1-form operator D

$$\mathsf{D} := \mathsf{d} + \omega^{\alpha\alpha} y_{\alpha} \partial_{\alpha} + \bar{\omega}^{\dot{\alpha}\dot{\alpha}} \bar{y}_{\dot{\alpha}} \bar{\partial}_{\dot{\alpha}} - i[A, \bullet]. \tag{30}$$

# unfolded Yang-Mills equations

• Unfolded consistent system for Yang-Mills theory

$$dA + [A, A] = \frac{1}{4} e^{\alpha}{}_{\dot{\beta}} e^{\alpha \dot{\beta}} \partial_{\alpha} \partial_{\alpha} F|_{\dot{y}=0} + \frac{1}{4} e_{\beta}{}^{\dot{\alpha}} e^{\beta \dot{\alpha}} \bar{\partial}_{\dot{\alpha}} \bar{\partial}_{\dot{\alpha}} \bar{F}|_{y=0},$$
(31)

$$DF = \frac{1}{N+1} e \partial \bar{\partial} F + iN[\frac{1}{N(N+1)} e \partial \bar{y} F, \frac{1}{N}F] - iey \bar{\partial} \frac{1}{N+2} [\frac{1}{N+2}\bar{F}, F] + \\ + [\frac{i}{(N+1)(N+2)} ey \bar{\partial} \bar{F}, F] + \frac{1}{2} ey \bar{y} [\frac{N+3}{(N+1)(N+2)} [\frac{1}{N+2}\bar{F}, F], F] + \\ + \frac{3}{2} ey \bar{y} [\frac{1}{(N+1)(N+2)} [\frac{1}{N}F, \bar{F}], F] + ey \bar{y} [\frac{1}{N+2} [\frac{1}{N+2}\bar{F}, F], \frac{1}{N}F],$$
(32)

plus a conjugate equation for  $\bar{F}$  and the  $\Omega$ -flatness equation.

• Spectrum of fields: 1-form  $\Omega$ , 1-form A, 0-form master-fields F(Y|x) and  $\overline{F}(Y|x)$ 

$$(N - \bar{N})F = 2F, \quad (N - \bar{N})\bar{F} = -2\bar{F}.$$
 (33)

 Symmetries: diffeomorphism-invariance, global (after fixing Ω) Poincaré associated to Ω, local YM associated to A. The YM symmetry is

$$\delta A(x) = \mathsf{D}\varepsilon(x), \quad \delta F(Y|x) = i[\varepsilon(x), F(Y|x)], \quad \delta \bar{F}(Y|x) = i[\varepsilon(x), \bar{F}(Y|x)]. \tag{34}$$

## unfolding maps

One can think of the equation

$$\mathsf{D}F = \frac{1}{N+1} e \partial \bar{\partial}F + i N[\frac{1}{N(N+1)} e \partial \bar{y}F, \frac{1}{N}F] + \dots$$
(35)

as defining an unfolding map from x-space to Y-space

$$F_{\alpha\alpha}(x)|_{on-shell} \to F(Y|x) \to \mathcal{F}(Y) := F(Y|x=0).$$
(36)

The first arrow is explicitly realized by

$$F(Y|x) = e^{Dy\bar{y}}F_{\alpha\alpha}(x)y^{\alpha}y^{\alpha}e^{-Dy\bar{y}}.$$
(37)

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The field  $\mathcal{F}(Y)$  carries precisely the same information as on-shell  $F_{\alpha\alpha}$  does.

- In a sense, spinors Y effectively replace x<sup>αα̇</sup> for on-shell configurations, hence being conjugate to helicity spinors resolving light-like momenta p<sub>αα̇</sub> = π<sub>α</sub>π̄<sub>α</sub>.
- This is how the unfolded system imposes e.o.m. on primary fields: via (36), it maps 4d space-time fields onto an effectively 3d hypersurface (in the sense that  $y^{\alpha} \bar{y}^{\dot{\alpha}}$  is a light-like vector).

## unfolding maps

Consider the abelian case in Cartesian coordinates

$$(\frac{\partial}{\partial x^{\mu\dot{\mu}}} - \frac{1}{N+1}\partial_{\mu}\bar{\partial}_{\dot{\mu}})F(Y|x) = 0, \qquad (38)$$

$$F(Y|x) = e^{y\bar{y}\frac{\partial}{\partial x}}F_{\alpha\alpha}(x)y^{\alpha}y^{\alpha} = F_{\alpha\alpha}(x+y\bar{y})y^{\alpha}y^{\alpha}.$$
(39)

A plane-wave solution is

$$A_{\alpha\dot{\alpha}}(x) = \pi_{\alpha}\bar{\mu}_{\dot{\alpha}}e^{i\pi_{\beta}\bar{\pi}_{\dot{\beta}}x^{\dot{\beta}\dot{\beta}}} + c.c., \quad F(Y|x) = i\bar{\pi}_{\dot{\alpha}}\bar{\mu}^{\dot{\alpha}}(\pi_{\alpha}y^{\alpha})^{2}e^{i\pi_{\beta}\bar{\pi}_{\dot{\beta}}(x^{\dot{\beta}\dot{\beta}}+y^{\beta}\bar{y}^{\dot{\beta}})}$$
(40)

with  $\bar{\mu}_{\dot{\alpha}}$  being an arbitrary reference spinor, defined up to a gauge transformation  $\bar{\mu}_{\dot{\alpha}} \rightarrow \bar{\mu}_{\dot{\alpha}} + const \cdot \bar{\pi}_{\dot{\alpha}}$ .

• Putting *x* = 0, one has

$$\mathcal{F}(Y) = i\overline{\pi\mu}(\pi y)^2 e^{i\pi y\overline{\pi y}}$$
(41)

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which is a plane-wave Maxwell tensor formulated purely in Y-terms.

• Although we have derived the unfolded equations starting from postulating the form of F(Y|x), now this form per se is just one particular solution (namely, the solution to the (Y = 0)-boundary problem).

# unfolding maps

• Alternatively, one can think of unfolded equations as defining a Y-to-x map [Vasiliev 1404.1948]

$$\mathcal{F}(Y) \to F(Y|x) \to F_{\alpha\alpha}(x)|_{on-shell}.$$
 (42)

In this picture,  $\mathcal{F}(Y)$  is completely unconstrained aside from the helicity condition

$$(N - \bar{N})\mathcal{F}(Y) = 2\mathcal{F}(Y) \quad \Rightarrow \quad \mathcal{F}(Y) = \mathcal{F}_{\alpha\alpha}(y\bar{y})y^{\alpha}y^{\alpha}. \tag{43}$$

• In the abelian case, the first arrow in (42) is implemented by

$$F(Y|x) = \exp(\frac{1}{N+1} x^{\beta\dot{\beta}} \partial_{\beta} \bar{\partial}_{\dot{\beta}}) \mathcal{F}_{\alpha\alpha}(y\bar{y}) y^{\alpha} y^{\alpha}.$$
(44)

This generates a solution to the unfolded (and hence implicitly to Maxwell) equations for arbitrary  $\mathcal{F}_{\alpha\alpha}(y\bar{y})$ .

- In fact, relativistic dynamics can be realized without any reference to a space-time. An action principle for an arbitrary-mass bosonic field was constructed in [NM 2301.02207] on  $(Y, \tau)$ -space, where  $\tau$  is an additional scalar coordinate.
- Twistor construction probably arises from treating an unfolded system as defining an unfolding map from some complex plane in ℝ<sup>1,3</sup> × C<sup>2</sup> manifold, different from Y = 0 or x = 0.

#### conclusions

- an unfolded formulation of 4d pure Yang–Mills theory was constructed
- certain unfolding maps solving the equations were found
- perspectives:
  - inclusion of **charged matter**: should be straightforward, like for scalar electrodynamics [NM 2402.14164].
  - introduce **supersymmetry** and manifest **conformal symmetry**: corresponding gauge 1-form of (super)conformal gravity should be introduced, which requires modifications of the unfolding technique
  - **quantization**: can be performed along the lines of [NM 2208.04306] but with necessary modifications in order to include ghosts.
  - integrability: construct an explicit map  $\mathcal{F}(Y) \to F_{\alpha\alpha}(x)$  for non-abelian case
  - relation to **twistors**: reproduce twistor construction from unfolded formulation by projecting onto an appropriate complex plane

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